

Shock Scattering in Multiphase Flow Model

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Daniel E. Klem
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Multiphase flow models have been proposed for use in situations which have combined Rayleigh-Taylor (RTI) and Richtmyer-Meshkov (RMI) instabilities[2, 3]. Such an approach works poorly for the case of a heavy to light shock incidence on a developed interface. The physical origin of this difficulty is traced to an inadequate model of the interfacial pressure term as it appears in the momentum and turbulence kinetic energy equations. Constraints on the form of a better model from a variety of sources are considered. In this context it is observed that a new constraint on closures arises. This occurs because of the discontinuity within the shock responsible for the RMI. The proposed model (Shock Scattering) is shown to give useful results.

Introduction

Multiphase flow models have been proposed for use in situations which have combined Rayleigh-Taylor (RTI) and Richtmyer-Meshkov (RMI) instabilities[2, 3]. Such an approach works poorly for the case of a heavy to light shock incidence on a developed interface. This occurs because of an inadequacy in the modeling of the interfacial pressures. The situation is illustrated in Fig. 1. A shock interacting with a complex surface produces transmitted and reflected waves which cannot be represented by the mean flow \tilde{u}_i . Note that this difference $u_i'' = u_i - \tilde{u}_i$ between the actual complex velocity u_i , and the mean flow \tilde{u}_i arises from a shock-mix interaction, and not from a shock-turbulence interaction. I.e., initially $u_i'' = 0$.

In most models fluid motions which cannot be represented by \tilde{u}_i are absorbed into a quantity like $k = \frac{1}{2\rho} \cdot \overline{\rho u_i'' u_i''}$.¹ If this is the case, then we should expect a source term in the time evolution equation for k of the form

$$\frac{\partial}{\partial t}(\rho k) + \dots = \dots + E'(\text{shocks, mix}) \quad (1)$$

¹This is the simplest case. One might also have multiple k 's for the small and large scales, direction specific k 's to capture anisotropies in the flow, etc.

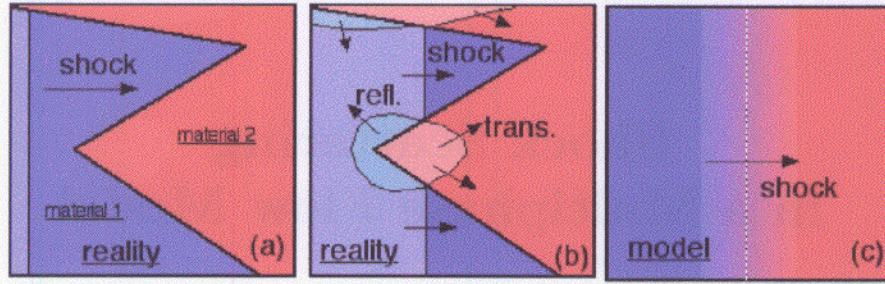


Figure 1: The figure shows a very schematic representation of the interaction of a shock with a mixed region. Part (a) is before the shock (incident from the left) interacts with the interface. Part (b) shows the interaction of the shock with the interface and the generation complex transmitted and reflected waves. Part (c) shows the view of this by the mix model.

where E' depends on the presence of a shock and a mixed region, but not on the presence of velocity fluctuations. I.e., a term which does not vanish just because $k = 0$. Such a term arises naturally in the context of a multiphase flow model, and I propose that it be called “shock scattering.”

The balance of this paper will consist of 1) a motivation for the use of multiphase flow models, 2) a description of how interfacial pressure terms arise, 3) consideration of the constraints on the modeling of these terms, 4) a description of an implementation of the model, and 5) a comparison to a couple of experiments.

Motivation: Mix is not just turbulence

Because this work relies heavily on the formalism used to derive the equations of multiphase flow[1], it is useful to review this so as to appreciate its applicability to the case of mixing² produced by a combination of the Rayleigh-Taylor and Richtmyer-Meshkov instabilities. In the presence of n materials or phases³ the mass or continuity equation must be split into n separate equations, one for each phase- r :

$$\frac{\partial \rho_r}{\partial t} + \frac{\partial}{\partial x_i}(\rho_r u_i) = 0, \quad \rho = \sum_r \rho_r \quad (2)$$

(The index i labels a direction and the index r labels a phase.) Note that this is simply the physics and not a modeling equation. It is valid at every point in space

²In this paper I am going to use the term “mix” to mean the interpenetration of two (or more) fluids. The subsequent molecular mix is not considered.

³I am going to use the term “phase” in the balance of this paper only because it has been used in the past. The reader might just as well understand this as “material” or “component.”

(trivially if the phase is not present). It contains only a single velocity u_i . This increase in complexity is required for the simple reason that one now needs to keep track of the locations of n different materials. Associated with this is a single (vector) momentum equation

$$\frac{\partial}{\partial t}(\rho u_i) + \frac{\partial}{\partial x_j}(\rho u_j u_i) = -\frac{\partial p}{\partial x_i} \quad (3)$$

and an analogous equation for the internal energy.

The need for a model arises when the complexity of the flow makes the calculation of details of the interpenetration (mix) impractical or unnecessary. In such a case it is hopefully not necessary to know ρ_r at every point in space and time, but rather it is sufficient to know only an average value $\overline{\rho_r}$. The bar here denotes an averaging operation which is to be understood in either an ensemble or (maybe) a volume sense. See reference [1]. The equation for the averaged quantity is obtained almost trivially

$$\frac{\partial \overline{\rho_r}}{\partial t} + \frac{\partial}{\partial x_i}(\overline{\rho_r u_i}) = 0, \quad (4)$$

where the second term illustrates the problem. This term contains an unknown correlation between the presence of the phase- r (ρ_r) and the velocity (u_i). Hence the problem of mix modeling reduces to that of modeling the correlation $\overline{\rho_r u_i}$.

As an aside it is useful to consider a path commonly taken in mix modeling. One can define both an average density $\overline{\rho}$ and a mass weighted average velocity $\tilde{u}_i = \overline{\rho u_i} / \overline{\rho}$ without regard to the presence or absence of a particular phase. From this one can define a velocity fluctuation $u_i'' = u_i - \tilde{u}_i$ which makes it possible to write the previous equation as

$$\frac{\partial \overline{\rho_r}}{\partial t} + \frac{\partial}{\partial x_i}(\overline{\rho_r} \tilde{u}_i) = -\frac{\partial}{\partial x_i}(\overline{\rho_r u_i''}) \quad (5)$$

Since the advection term on the left-hand side contains the same velocity for every phase, this term will not produce any mixing. The problem then reduces to modeling the correlation in the term on the right side $\overline{\rho_r u_i''}$. At this point it is not uncommon to concede defeat by invoking a gradient diffusion closure. I.e., taking

$$\overline{\rho_r u_i''} = -D \frac{\partial \overline{\rho_r}}{\partial x_i} \quad (6)$$

where $D \propto \sqrt{k}l$, for instance. While a closure such as this has a very definite practical advantages in its implementation, its utility for modeling instability driven mix is unproven. Given that it has its motivation in the ideas of isotropic turbulence and analogies to kinetic theory, it is not obvious that such a closure should be applicable to the present problem. Such closures are often accompanied by complicated turbulence

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same as the gradient of the average of the pressure[1].⁴ This term is typically modeled as drag between the two phases.

Before preceeding with this, it is worthwhile to consider whether anything was obtained from this exercise. The answer to this is an emphatic yes, as the model at this point is able to produce mixing (and demixing). To see this consider a simple problem with a constant pressure gradient $g_i = \frac{\partial p_r}{\partial x_i}$ with the fluids initially at rest. Then the momentum equation initially reduces to

$$\frac{\partial}{\partial t}(f_r \rho_r \tilde{u}_i) = -f_r g_i \quad (10)$$

From this it is clear that the acceleration of each phase- r will go like $1/\rho_r$. The subsequent velocity separation will result in either mixing or demixing depending on the sign of g_i and the initial conditions. Models based on this formalism are also inherently anisotropic and will provide a sort of automatic scale separation if a model is included for the Reynolds stress (i.e., a k-equation, etc.). The costs of this are interfacial pressures to model and phase specific Reynolds stresses.

Drag is not enough

As was indicated above, the interfacial pressures which appear in the momentum equation are typically modeled as drag between the phases. This is not adequate in the presence of shocks. To see this it is useful to consider the Reynolds stress which appears in the momentum equation

$$T_{r,ij} = \frac{1}{f_r} \overline{X_r \rho u''_{r,i} u''_{r,j}} \quad (11)$$

From this one can obtain an equation for the energy not resolved in the $\tilde{u}_{r,i}$ if we proceed as follows. First, assume that all the anisotropies are handled by the mean flow variables $\tilde{u}_{r,i} = \overline{\rho_r u_i} / (f_r \rho_r)$. If this is the case, then one can define a phase specific turbulence kinetic energy

$$k_r = \frac{1}{2\rho_r} \sum_i T_{r,ii} \quad (12)$$

If we make the further assumption that all the phases have similar velocity fluctuations k_r , then one can, without loss of information, sum over the phases to define a total turbulence kinetic energy

$$k = \frac{1}{\rho} \sum_r f_r \rho_r k_r = \frac{1}{2\rho} \sum_{r,i} f_r T_{r,ii} \quad (13)$$

⁴I probably differ from reference [1] on the interpretation of the resulting terms. The form given here is clearer in any case, and likely more correct.

The usual manipulations starting from the momentum equation (along with the assumptions above) eventually produce

$$\begin{aligned} \frac{\partial}{\partial t}(\rho k) + \frac{\partial}{\partial x_i}(\tilde{u}_i \rho k) &= T_{in} \sum_r f_r \frac{\partial \tilde{u}_{r,i}}{\partial x_i} + \sum_r \frac{\partial}{\partial x_i} \left(X_r \frac{\rho}{2} u''_{r,k} u''_{r,i} u''_{r,i} \right) \\ &+ \underbrace{\sum_r \left[\sum_i \tilde{u}_{r,i} \left(\frac{\partial X_r}{\partial x_i} p_r - p_r \frac{\partial f_r}{\partial x_i} \right) \right]}_{\text{surface pressure terms}} \end{aligned} \quad (14)$$

where the first line contains the terms analogous to the single material case and the second line contains the terms arising from the surface pressure terms in the momentum equation. These later terms are obviously not small and have been modeled previously as sources of the energy lost from the velocity slip due to drag and added mass effects[2, 3]. This is inadequate in the case of a shock interacting with a region containing multiple materials. Further, if a mixed region is initially at rest then $u''_{r,i} = 0$, and as a consequence $T_{in} = 0$ and similarly for the triple correlation. Hence, only the surface pressure term is available to generate k as is required according to the argument presented in the introduction. This appears plausible since neither the pressure nor the mean flow velocities which appear in this term vanish. The model for this will be called “shock scattering” as was explained in the introduction.

Shock Scattering

At this point it is clear that there exists a need for a pair of additional terms in the momentum equation and the k -equation. I.e., $E_{r,i}$ and E' as in

$$\frac{\partial}{\partial t}(f_r \rho_r \tilde{u}_i) + \frac{\partial}{\partial x_j}(f_r \rho_r u_j u_i) = \dots + E_{r,i} \quad (15)$$

$$\frac{\partial}{\partial t}(\rho k) + \frac{\partial}{\partial x_i}(\tilde{u}_i \rho k) = \dots + E' \quad (16)$$

Constraints on these two terms arise from the following

1. Conservation of energy and momentum (terms in both the equation for k and the equation for \tilde{u}_i are clearly required.)
2. Invariance of the term added to the k equation under changes of the frame of reference.
3. No dimensional constants in either term.
4. Both terms should be independent of the length scale.
5. Well behaved in the presence of shocks.

Well behaved in the presence of shocks

Substantial constraints are placed on the form of $E_{r,i}$ and E' (as well as any other term which is used in a mix model) by the requirement that these terms have meaningful behaviour in the presence of discontinuous solutions (i.e., shocks). Recall that there are subtle issues when shocks form in any system of differential equations. The two derivatives $\frac{\partial}{\partial x}$ and $\frac{\partial}{\partial t}$ are not defined (in the usual sense) at a discontinuity. For systems of conservation laws this can be dealt with through the ideas of generalized functions and weak solutions[5]. I.e.,

$$\text{an equation like:} \quad \frac{\partial \rho}{\partial t} + \frac{\partial Q(\rho)}{\partial x} = 0 \quad (17)$$

$$\text{is interpreted to mean:} \quad \iint_R \left\{ \rho \frac{\partial \phi}{\partial t} + Q(\rho) \frac{\partial \phi}{\partial x} \right\} = 0 \quad (18)$$

where ϕ is an arbitrary test function with compact support on R , ρ is some density, and $Q(\rho)$ is some flux. For continuous ρ and $Q(\rho)$ these two equations are equivalent and can be obtained from each other by integration by parts. If ρ or $Q(\rho)$ become discontinuous only the second equation actually has meaning. From these sorts of considerations one also obtains the jump condition $[\rho] \cdot U = [Q(\rho)]$ (where $[X]$ means the change in X across the shock). Because mix models do not generally appear in conservation form⁵, the situation with respect to discontinuous solutions is very murky indeed. Never-the-less, it is clear that the issue of the interpretation of these models in the presence of shocks does not go away just because it has been ignored to date. This issue may become worse in the models than in the Euler equations because of the presence of higher order derivatives and/or products of derivatives.

One can, never-the-less, see that a simple necessary condition exists for these terms to have meaning in the presence of shocks.⁶ If one considers a potential closure E' which appears on the right-hand side of some time evolution equation (of ρk for instance)

$$\frac{\partial}{\partial t}(\rho k) + \dots = \dots + E' \quad (19)$$

then a set of necessary conditions for this term to be meaningful in the presence of

⁵This has never happened to my knowledge.

⁶I want to emphasize that this is a necessary but not necessarily sufficient condition for the terms in question to have meaning. If the model were expressed in conservation form, then that would clearly be sufficient. The question as to whether some clever mathematics exists (or can be invented) to give meaning to the model without putting it into conservation form appears to be open.

shocks is⁷

$$\int_{\text{shock}} E' dt = \begin{cases} \cdot \text{finite} \\ \cdot \text{non-zero} \\ \cdot \text{depends only on the jumps across the shock} \end{cases} \quad (20)$$

In general one can show that “good” terms “work” by using integration by parts to move the derivatives off the discontinuous functions (so to speak). For “bad” terms no such manipulations appear possible, and it seems to be necessary to introduce a particular continuous form for the step, do the integration explicitly, and then show that the result is not defined (and therefore “does not work”) as the step is allowed to become discontinuous. Since the latter is somewhat more transparent, it will be used throughout. Consider a test function

$$u^{\natural} = u^{\natural}(x + ct) = \begin{cases} u_1 & \text{if } x + ct < 0 \\ u_1 + (x + ct) \frac{\Delta u}{\Delta} & \text{if } 0 < x + ct < \Delta \\ u_2 = u_1 + \Delta u & \text{if } \Delta < x + ct \end{cases} \quad (21)$$

i.e., a linear ramp in u which goes from u_1 to u_2 over an interval Δ and which propagates with a velocity c . (The superscript \natural is used to indicate a discontinuous function.) Then it is trivial to see that in the limit $\Delta \rightarrow 0$ a continuous function times the derivative of a discontinuous function is O.K.

$$\int_{\text{shock}} f \frac{\partial u^{\natural}}{\partial x} dt \longrightarrow f \frac{\Delta u}{c} \quad \text{An example of such a term is the pressure gradient in the momentum equation.} \quad (22)$$

Several other terms also work. The product of a discontinuous function and the derivative of a discontinuous function is O.K.

$$\int_{\text{shock}} h^{\natural} \frac{\partial u^{\natural}}{\partial x} dt \longrightarrow (h_1 + \frac{\Delta h}{2}) \frac{\Delta u}{c} \quad \text{Like the } pdV \text{ term in the internal energy equation.} \quad (23)$$

The product of a continuous function and the n 'th derivative of a discontinuous function also works

$$\int_{\text{shock}} h \frac{\partial^n u^{\natural}}{\partial x^n} dt \longrightarrow (-1)^{n-1} \frac{\partial^{n-1} h}{\partial x^{n-1}} f \frac{\Delta u}{c} \quad (24)$$

This last case follows, roughly speaking, because one can take arbitrary derivatives of δ -functions. (Although this might be hard to actually make work in a real code ...)

There are also at least a couple of terms which do not work.

The product of the derivatives of two discontinuous functions

$$\int_{\text{shock}} \frac{\partial g^{\natural}}{\partial x} \frac{\partial u^{\natural}}{\partial x} dt \longrightarrow \frac{\Delta g \cdot \Delta u}{c \cdot \Delta} \longrightarrow \infty \quad (25)$$

⁷The requirement that the result be non-zero is not strictly necessary, zero being a perfectly good number. However, such a term is clearly of no use in modeling the shock-mix interaction.

and the product of a discontinuous function and the second derivative of a discontinuous function

$$\int_{\text{shock}} g^{\natural} \frac{\partial^2 u^{\natural}}{\partial x^2} dt \longrightarrow -\frac{\Delta g \cdot \Delta u}{c \cdot \Delta} \longrightarrow -\infty \quad (26)$$

are both undefined. This is roughly the equivalent of saying that there is no meaning to multiplying δ -functions. (Note that these two cases are also related by an integration by parts.) Note also that the first of these rules out the use of $\frac{\partial \rho}{\partial x} \cdot \frac{\partial p}{\partial x}$.

Some terms are zero.

These are a couple of almost trivial examples. The integral over a shock of either a continuous or discontinuous function vanishes.

$$\int_{\text{shock}} f dt = \int_{\text{shock}} g^{\natural} dt = 0 \quad (27)$$

The point here being that one requires a certain degree of singular behavior out of the term in order to get a non-zero contribution as the width of the shock goes to zero. More complicated terms can also be zero. For instance

$$\begin{aligned} \int_{\text{shock}} \frac{\partial}{\partial x} \left(g^{\natural} \frac{\partial u^{\natural}}{\partial x} \right) dt &= \int_{\text{shock}} \frac{\partial g^{\natural}}{\partial x} \frac{\partial u^{\natural}}{\partial x} + \int_{\text{shock}} g^{\natural} \frac{\partial^2 u^{\natural}}{\partial x^2} \\ &= \frac{\Delta g \cdot \Delta u}{c \cdot \Delta} - \frac{\Delta g \cdot \Delta u}{c \cdot \Delta} = 0 \end{aligned} \quad (28)$$

Figure 2 shows a rather schematic representation of this potential source term. The point to appreciate is that one might have difficulties integrating this numerically and actually getting zero.

Terms which “do not work” are commonly used in turbulence modeling.

Some of the terms indicated above which “do not work” are used in turbulence modeling in cases where there are typically no shocks. An example of such a situation is a common closure for the Reynolds stress[7].

$$\overline{\rho u_i'' u_i''} = T = - \underbrace{\mu_T \frac{4}{3} \frac{\partial u}{\partial x}}_A + \underbrace{\frac{2}{3} \rho k}_B, \quad \mu_T = \rho \sqrt{k} l \quad (29)$$

The labels A and B will be used in the discussion below as these two parts of the closure behave in a very different manner in the presence of a shock. This term appears in both the momentum equation and in the equation for k , acting as a sort of

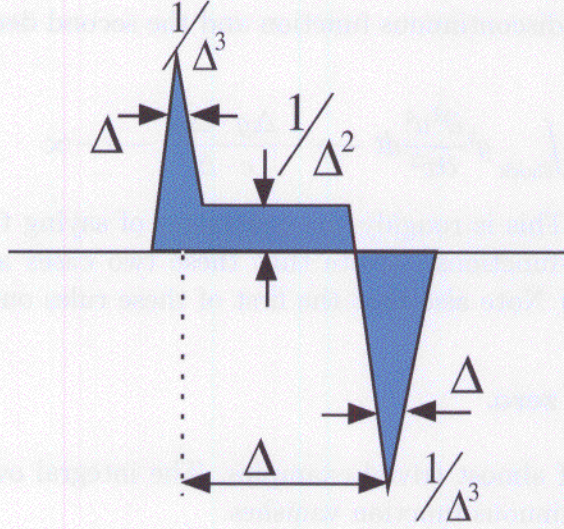


Figure 2: The figure shows the complex singular behaviour of the term in eqn.28. Labels show proportionality to Δ . This term, never-the-less, integrates to zero.

turbulent pressure which can move energy between the mean flow and the unresolved scales k .

$$\frac{\partial}{\partial t}(\rho u) + \dots = \dots - \frac{\partial T}{\partial x} = \dots \underbrace{\frac{\partial}{\partial x} \left(\mu_T \frac{4}{3} \frac{\partial u}{\partial x} \right)}_A - \underbrace{\frac{2}{3} \frac{\partial}{\partial x}(\rho k)}_B \quad (30)$$

$$\frac{\partial}{\partial t}(\rho k) + \dots = \dots - T \frac{\partial u}{\partial x} = \dots \underbrace{\mu_T \frac{4}{3} \left(\frac{\partial u}{\partial x} \right)^2}_A - \underbrace{\frac{2}{3} \rho k \frac{\partial u}{\partial x}}_B \quad (31)$$

By the criteria given above the B terms “work.” The A terms do not. The A term in the k -equation contains the product of two derivatives of a discontinuous function, and will make an undefined contribution to k .

$$\int_{\text{shock}} \mu_T \frac{4}{3} \left(\frac{\partial u}{\partial x} \right)^2 dt = \rho \sqrt{k} l \cdot \frac{4}{3} \cdot \frac{(\Delta u)^2}{c \cdot \Delta} \propto \frac{1}{\text{zone size!}} \quad (32)$$

The corresponding A term in the momentum equation has no net effect on the momentum, but because it acts to accelerate and decelerate the flow at times at which the flow velocity is very different (recall the discontinuous change in u), it can never-the-less change the energy in the mean flow.

In any code, of course, shocks always have a finite width so that in practice “bad terms” as identified here will have large but finite effects due to shocks. In an Euler code (one with no explicit viscosity) these effects will be proportional to inverse powers

of the zone size (since shocks are typically spread over a few zones by artificial viscous effects of one sort or another). This means that models with such terms will prevent the code from reaching a converged answer as the zone size is reduced. In a code with explicit viscous effects, “bad terms” will produce effects which depend upon the viscosity. As shock interactions are generally thought to be independent of the actual viscosity and thermal conductivity which determine the width of the shock[6], this would appear to be the wrong physics.

These observations are not entirely new. At least one author[8] understood that some of these terms get too big, and that limiters must be used. While anecdotal evidence suggests that the use of limiters may be more wide spread and not generally reported in the literature[4, 9], it is not clear that the fundamentally undefined character of these terms has been appreciated. To put this another way, the difficulty here goes beyond the idea of realizability constraints.[7]

Lastly, one should ask if there are any ways around the difficulties described in this section. If the model were to act upon the mean flow variables so as to induce a correct shock width (in the average sense), then all the “bad” terms would be defined. Such an interaction is expected in some sense, of course, because the Reynolds stress term in the momentum equation can have the form of a viscosity. The usual closure will presumably not work in the present case because it is (at best) a shock-turbulence interaction and not a shock-mix interaction. Even with a closure which induces the correct shock width, it might be a difficult task to get overall reasonable behaviour. I.e., it is not clear that a “bad” term with a value of Δ proportional to the average shock width induced by the passage through a mix material would give reasonable behaviour. Such a model would also require that the resolution in the simulation be adequate to resolve the shock width.

Dimensional Analysis

If the new term in the k -equation is to not have a dimensionful constant out front, and if it does not depend on the length scale l in the problem, then it is straightforward to show that

$$\frac{\partial}{\partial t}(\rho k) + \dots = C \cdot \rho^\alpha u^{1+2\alpha} p^{1-\alpha} \frac{\partial}{\partial x} \quad (33)$$

where the derivative $\frac{\partial}{\partial x}$ could be applied to any combination of the powers of ρ , u , and p . At this point α remains a free parameter.

Invariance

It is well known that E' must be invariant under a change in coordinate systems. The term $u^{1+2\alpha}$ above might break such an invariance. This can be “fixed” either by

taking the exponent of u to be zero so that $\alpha = -1/2$, or by taking the exponent to be one so that $\alpha = 0$ and letting the derivative operate on it. These two cases result in

$$\frac{\partial}{\partial t} + \dots = C \cdot \sqrt{\frac{p}{\rho}} \frac{\partial p}{\partial x} \quad \text{or} \quad \frac{\partial}{\partial t} + \dots = C \cdot p \frac{\partial u}{\partial x} \quad (34)$$

The left one being roughly a pressure gradient times a sound speed and the right one a $p\delta V$ work term.

Conservation of Energy and Momentum

Lastly, the need to conserve momentum and energy forces the selection of the right-hand term. The total energy equation is obtained by multiplying the momentum equation in two forms by u and adding these to the equations for k and internal energy. Conservation is achieved if the combined term $u \cdot E_{r,i} + E'$ either vanishes or forms a total divergence. The first of these would correspond to a purely local exchange of energy between the mean flow and k . The second case allows for energy transport as well as exchange. The first would require an inverse power of u in the term in the momentum equation and, therefore, appears to be unreasonable. Hence the only possible forms for $E_{r,i}$ and E' appear to be

$$E_{r,i} = C \cdot \frac{\partial p}{\partial x} \quad \text{and} \quad E' = C \cdot p \frac{\partial u}{\partial x} \quad (35)$$

which is exactly the same form as the $p\delta V$ work terms which exchange energy between the mean flow and internal energy. Note also that the term in the momentum equation must be a divergence so as to conserve momentum.

Non-dimensional factors

At this point we are required to specify the form of the non-dimensional factor C . As was discussed above, this term must be sensitive to 1) the presence of a mixed region, and 2) the presence of a shock. Toward this end I first introduce

$$H_i = F_i \sum_r f_r H_{r,i} \quad (36)$$

which is the product of two factors. The first F_i will be sensitive to the presence of a shock. The second (the sum) is sensitive to the presence of a mixed region. Specifically

$$H_{r,i} = \sum_{s \neq r} f_s \frac{|\rho_r - \rho_s|}{\rho_r + \rho_s} \quad (37)$$

| | | |
|------------|-------------------------|---------------------------------------|
| c_1 | $17.25 - 5.25 \cdot At$ | drag |
| c_2 | 0.75 | turbulent length scale w.r.t. l |
| c_4 | 0.09 | dissipation of turbulent KE |
| c_5 | 2.0 | mass diffusion |
| c_7 | 1.0 | turbulent KE diffusion |
| c_8 | 2.0 | length scale diffusion |
| c_{10} | 4.0 | shock scattering |
| c_{11} | 0.005 | mix trigger |
| c_{sss} | 0.0, 0.3 | compression / expansion scale factors |
| c_{lsc} | 1.0 | length scale source |
| c_{lsc2} | 1.0 | length scale due to diffusion |

Table 1: Parameters used in the simulations described below. As described in the text, some have been picked to fit the data, others are from the literature[2, 3].

so that $\sum_r f_r H_{r,i}$ is just a weighted sum of Atwood numbers. The F_i term is the n 'th root of a product over phases

$$F_i = \left[\prod_r F_{r,i} \right]^{\frac{1}{n}} \quad \text{where} \quad F_{r,i} = \begin{cases} 0 & \text{iff } \delta u_i < \delta u_l \\ 0.5 \left(\frac{|\delta u_i - \delta u_l|}{\delta \delta u} \right)^{c_{13c}} & \text{iff } \delta u_l < \delta u_i < \delta u_o \\ 1 - 0.5 \left(\frac{|\delta u_h - \delta u_i|}{\delta \delta u} \right)^{c_{13c}} & \text{iff } \delta u_o < \delta u_i < \delta u_h \\ 1 & \text{iff } \delta u_h < \delta u_i \end{cases} \quad (38)$$

and $\delta u_i = u_{i-\frac{1}{2}} - u_{i+\frac{1}{2}}$, $\delta u_o = c_{13a}$, $\delta \delta u = c_{13a} \cdot c_{13b}$, $\delta u_l = \delta u_o - \delta \delta u$, and $\delta u_h = \delta u_o + \delta \delta u$. While the algebra is a little tedious, the function F_i simply implements a smooth transition from zero to one as the relative velocity between two zone edges goes from less than $\delta u_o = c_{13a}$ to greater than δu_o . The final result is

$$\frac{\partial}{\partial t}(f_r \rho_r \tilde{u}_{r,i}) + \dots = \dots c_{10} \frac{\partial}{\partial x_i}(f_r p_r H_i) \quad (39)$$

$$\frac{\partial}{\partial t}(\rho k) + \dots = \dots c_{10} \sum_{r,i} f_r p_r H_i \frac{\partial \tilde{u}_{r,i}}{\partial x_i} \quad (40)$$

where c_{10} is a constant. Note that H_i must appear inside one derivative and outside the other so that the resulting combined term in the total energy equation is still a total divergence.

Length scale sources

As will be discussed below, changes were also required to the length scale source terms in order to match the data. The dilatation term was given separate scale factors for

expansion and compression, and an additional source which allows purely turbulent mix to generate its own length scale has been added.

In addition to the above, it was found necessary to limit the development of additional velocity separation during shocks so as to prevent a sort of double counting from occurring. This is accomplished by interpolating between the pressure gradient given above, and the form which occurs in the single fluid case. This interpolation is based on F_i defined above to identify shocks.

Implementation

The model has been implemented as a 1-D Lagrangian hydrocode. The final form is as follows.

$$\frac{\partial}{\partial t}(Af_r\rho_r) + \frac{\partial}{\partial x}(Af_r\rho_r\tilde{u}_r) = 0 \quad (41)$$

$$\begin{aligned} \frac{\partial}{\partial t}(Af_r\rho_r\tilde{u}_r) + \frac{\partial}{\partial x}(Af_r\rho_r\tilde{u}_r\tilde{u}_r) &= -Af_r\frac{\partial p}{\partial x} - \boxed{Af_r\frac{\partial T}{\partial x}}^{\text{Reynolds stress}} + A\sum_s(D_{rs} + M_{rs}) \\ &+ \boxed{c_{10}A\frac{\partial}{\partial x}(p \cdot f_r H)}^{\text{shock scattering}} + Af_r S_{u,r} \end{aligned} \quad (42)$$

$$\frac{\partial}{\partial t}(Af_r\rho_r e_r) + \frac{\partial}{\partial x}(Af_r\rho_r e_r\tilde{u}_r) = -h_r p \frac{\partial}{\partial x}(A\tilde{u}) + Af_r\epsilon + Af_r S_{e,r} \quad (43)$$

$$\begin{aligned} \frac{\partial}{\partial t}(Apk) + \frac{\partial}{\partial x}(Apk\tilde{u}) &= \boxed{-AT\frac{\partial \tilde{u}}{\partial x}}^{\text{Reynolds stress}} - \frac{\partial}{\partial x}\left(A\rho D_k \frac{\partial k}{\partial x}\right) - \epsilon A \\ &+ \boxed{\sum_r f_r \tilde{w}_r \frac{\partial p}{\partial x}}^{\text{deleted}} + \boxed{c_{10}\sum_r f_r p H \frac{\partial}{\partial x}(A\tilde{u}_r)}^{\text{shock scattering}} \\ &+ \sum_{r<s}(\tilde{u}_s - \tilde{u}_r)(D_{rs} - M_{rs}) \end{aligned} \quad (44)$$

$$\frac{\partial l}{\partial t} + (\tilde{u} + u_l)\frac{\partial l}{\partial x} = -\frac{1}{A}\frac{\partial}{\partial x}\left[AD_l\frac{\partial l}{\partial x}\right] + \boxed{c_{ss}\frac{\partial \tilde{u}}{\partial x}l}^{\text{l-scale}} + S_l + \boxed{S_{l2}}^{\text{l-scale}} \quad (45)$$

where

$$S_l = c_{lsc} \cdot \frac{\sum_{r>s} f_r f_s \left(\frac{2\rho_{rs}}{\rho_r + \rho_s}\right)^{\frac{1}{2}} (\tilde{u}_r - \tilde{u}_s)}{\sum_{r>s} f_r f_s} \quad \text{and} \quad \boxed{S_{l2} = c_{lsc2} \cdot \frac{\sum_{r>s} f_r f_s \left(\frac{2\rho_{rs}}{\rho_r + \rho_s}\right)^{\frac{1}{2}} (\tilde{u}_r - \tilde{u}_s)}{\sum_{r>s} f_r f_s}}^{\text{l-scale}} \quad (46)$$

$$u_l = \frac{\sum_{r>s} f_r f_s (f_r - f_s)(\tilde{u}_s - \tilde{u}_r)}{\sum_{r>s} f_r f_s} \quad \boxed{\tilde{u} = \sum_r f_r \tilde{u}_r}^{\text{changed}} \quad (47)$$

$$D_{rs} = -c_1 \frac{\rho_{rs} f_r f_s}{l} |\Delta_{rs}| \Delta_{rs} \quad \text{with} \quad \Delta_{rs} = (\tilde{u}_r - \tilde{w}_r) - (\tilde{u}_s - \tilde{w}_s) \quad (48)$$

$$\tilde{w}_r = -\frac{D}{f_r \rho_r} \frac{\partial}{\partial x} (f_r \rho_r) \quad \text{with} \quad D = c_5 \sqrt{k} l_t, l_t = c_2 l \quad (49)$$

$$\boxed{\overset{\text{Reynolds stress}}{T = -\mu_T \frac{4}{3} \frac{\partial \tilde{u}}{\partial x} + \frac{2}{3} \rho k}} \quad \text{limited by} \quad 0 < T < \frac{5}{4} \rho k \quad (\text{see [8]}) \quad (50)$$

As has been indicated previously, this is derived from the work of Youngs[2, 3, 4]. Deviations from that work are indicated in the boxes. They fall into four groups.

- Shock scattering terms (proportional to c_{10}) appear in the momentum and k -equations.
- Reynolds stress terms of a different sort also appear in these two equations. Note the need for a limiter on T .
- The definition of \tilde{u} as it appears in the $p\delta V$ work term in the energy equation has been changed. This allows a “bad” term to be deleted from the k -equation as discussed above.
- Two length scale source terms in the length scale equation are changed.

The parameter set used in the simulations is given in Table 1. M_{rs} is taken to be 0.

Comparison to Experiments

This effort was originally motivated by the known inability of the model to handle heavy to light RMI. This section compares the model to two experiments. The first is a heavy to light reshock experiment in which improved behaviour is observed. Since the changes (particularly those to the length scale sources) will change the behaviour of the model in general, a comparison is made to an acceleration / deceleration “rocket rig” experiment. A reasonable agreement with the data is obtained, with the two experiments together substantially constraining the model.

Reshock Experiment

The first comparison is to the reshock experiment of Vetter and Sturdevant[10]. This is an air-SF₆ Mach 1.5 shock tube experiment. The initial interface is formed by a flat membrane. The incident shock brakes the membrane and then is reflected from the end wall (62cm from the initial interface location). This reflection (a heavy to light shock) accelerates the interface approximately 3.4 msec. after the initial shock and is observed to cause a substantial growth in the mixing rate.

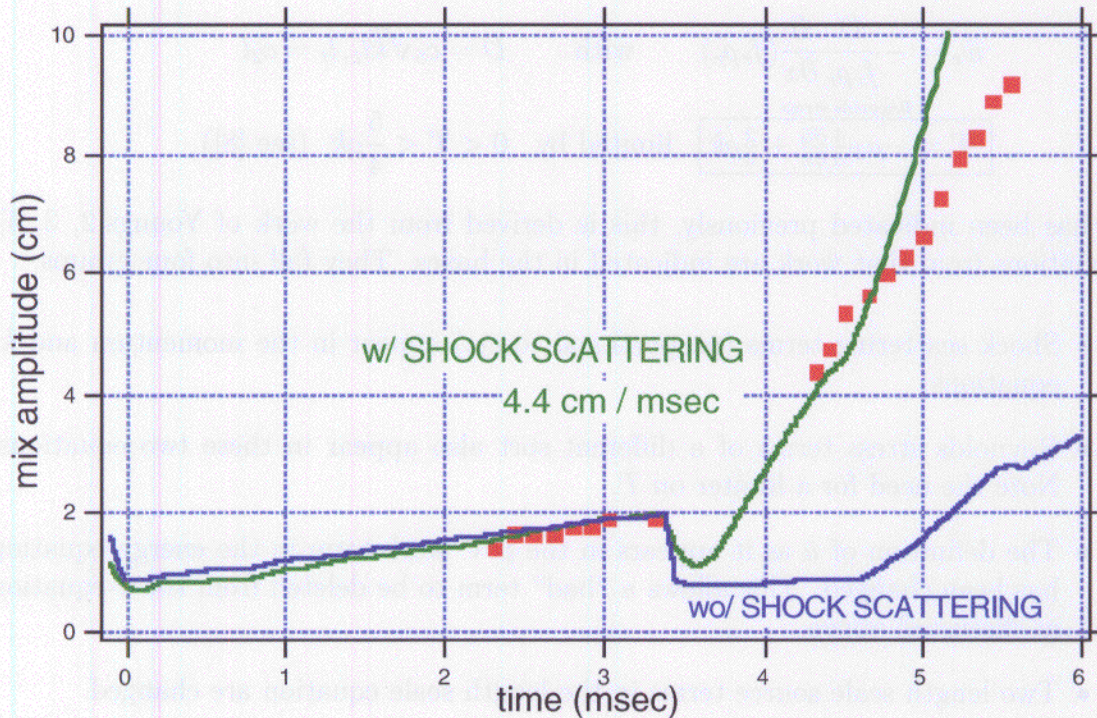


Figure 3: The figure shows a comparison between the measured and modeled values of the total mix width in the reshock experiment. The red points are from the experiment. The blue and green solid lines show the results of the model with and without the shock scattering. Reasonable agreement is obtained up until the arrival of the reflected rarefaction at about 4.5 msec.

The simulation of this experiment is carried out with ideal gas equations-of-state ($\gamma = 1.402$ for air and $\gamma = 1.0935$ for SF_6). The initial value of the length scale l in the model was adjusted so that the width of the mix region measured at 3 msec. in the experiment was reproduced by the model. The results are compared to the experiment in Fig. 3. Good agreement is obtained up until the arrival of a reflected rarefaction at 4.5 msec. The behaviour of the unmodified model is also shown.⁸

Acceleration / Deceleration Experiment

The second comparison is to the acceleration/deceleration experiment of Smeeton and Youngs[11]. This was an immiscible fluid “rocket rig” experiment carried out at AWE in which the tank first experienced a constant acceleration, followed by a coast, followed by a more or less constant deceleration, followed by another coast. The

⁸A reasonable effort was made to tune the unmodified model to reproduce the data. While this was not successful, it is difficult to really prove that is not possible.

turbulent mixing layer was observed to first grow, then demix during the deceleration, and then resume growing during the final coast phase. This subsequent regrowth is interpreted as being due to the turbulence[2].

The two fluids here (actually a calcium chloride solution and hexane, densities of 1.142 g/cm³ and 0.66 g/cm³) are modeled with a scaled ideal gas equation-of-state. The initial temperature distribution through the problem is set to produce the pressure gradient required to give a uniform initial acceleration. Subsequent changes in the acceleration are implemented through changes to the external pressure boundary conditions and necessarily produce a series of small shocks (below the threshold for the shock finder). The results of the simulation are compared to the experiment in Fig. 4. Reasonable agreement is obtained.

This is a significant experiment because it tests not only the multiphase flow part of the model, but also the kl turbulence part. A substantial effort was devoted to finding parameters which would simultaneously fit both this experiment and the reshock experiment. The nature of the difficulty is as follows. The length scale l is a sort of quasi-conserved quantity. I.e., just because one would like more $\int l dx$, does not mean the terms on the right-hand side will produce it. In order to grow the mix region, the model must increase $\int l dx$. In the case of the RTI, the S_l term generates the required l . In the current case the S_{l2} term was added to enable the growth of the mixing region in the reshock experiment. It does this by allowing turbulence to generate l after the passage of the shock. While it appears possible to match the Vetter experiment with a variety of values of c_{10} and c_{lsc2} (they are anti-correlated), not perturbing the acceleration / deceleration experiment is more difficult. This sets an upper limit on the value of c_{lsc2} (larger values produce too much mix at late times). The resulting value of $c_{10} = 4$ appears large in that it implies that the energy removed from the main flow and moved into k is about the same size as that moved into internal energy.⁹ If the change in k produced by the passage of the shock is, in fact, too big, then another mechanism for producing l may be required.

Conclusions

This paper has proposed an innovative method to improve the behaviour of an existing model for the mix from combined RMI and RTI. The added terms improve the modeling of the interfacial pressures. Reasonable agreement is obtained with two experiments; one RM and the other RT. Additional comparisons to other mix experiments are required. A further examination of the modifications to the l equation is planned.

⁹Recall that $\sum_r f_r H_{r,i}$ can not be greater than $\frac{1}{4}At$.

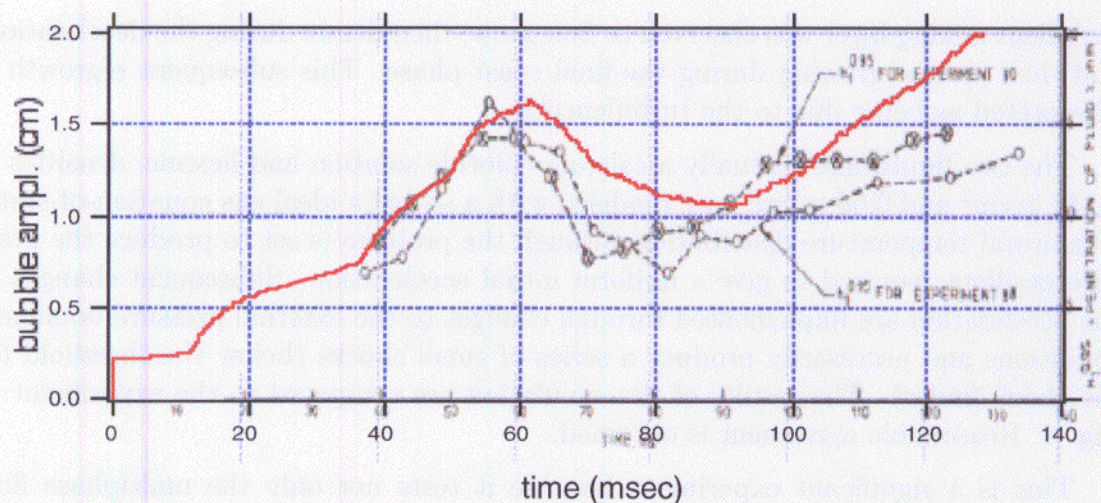


Figure 4: The figure shows a comparison between the measured and modeled values of the bubble amplitude. The model results are shown in red. Reasonable agreement is obtained.

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